# PRODUCT SPECIFICATION

2nd. EDITION

# MACHINE TYPE 6 BUTTON CONTROL PAD

MODEL NO.

MK-1653-50

## 1) CONTENTS

1) CONTENTS		P.2
2) RANGE OF APPLICATION		P.3
3) MODEL NO.		P.3
4) EXTERNAL APPEARANCE		P.3
5) FEATURES AND MACHINE TO BE ADAPTED		P.4
6) MEASURES OF THE BODY		P.5
7) ENVIROMENTAL CONDITIONS WHEN USING	i i	P.5
8) ELECTRIC SPECIFICITY		P.5
9) ACCESS SEQUENCE	•	P.6~
10) MECHANISM OF THE PARTS		P.8

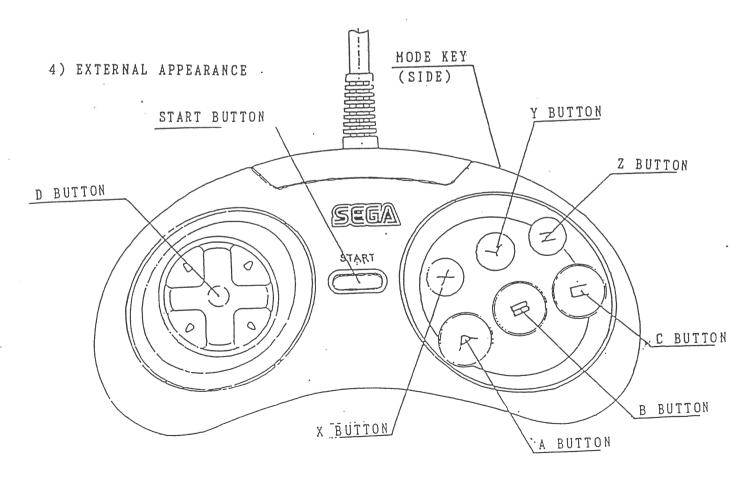
# 2) RANGE OF APPLICATION

This specification applies for the procucts below made by SEGA ENTERPRISES.

#### 6 BUTTON CONTROL PAD

#### 3) MODEL NO.

JAPANESE VERSION SJ-6000
U.S. VERSION T.B.D.
E.C. VERSION T.B.D.



### 5) FEATURES AND MACHINE TO BE ADAPTED

Compared to present control pad,4 buttons will be added. That is, 3 buttons(X,Y,Z) on the controlling surface and MODE KEY on the upper right side. So, including the START button, there are 8 buttons altogether.

This pad is interchangeable to the present one. You can operate almost any game soft that are now on sale and if there is any trouble on operation, it will work properly by transfering to 3 button mode(described below).

By pushing the mode button when switching on the console, this pad transfers to 3 button mode and it works just the same as the present pad.

Caution: You cannot transfer into 3 button mode by the game soft programme. That is, it does not transfer to 3 button mode by pushing reset button and MODE KEY at same time.

Machines to be adapted: MEGADRIVE, MEGADRIVE 2, TERA DRIVE, WONDER-MEGA

- 6) MEASURES OF THE BODY

• MEASURES  $140(W) \times 74(D) \times 26(H)$  mm

● LENGTH OF CABLE 1.2 m

WEIGHT

120 g

7) ENVIROMENTAL CONDITIONS WHEN USING

OPERATING CONDITION 0°C  $\sim 40$ °C 10%RH  $\sim$  80%RH(Do not let it dew)

STORAGE CONDITION  $-10\,^{\circ}\text{C}$   $\sim 70\,^{\circ}\text{C}$  5%RH  $\sim$  95%RH

8) ELECTRIC SPECIFICITY

ELECTRIC VOLTAGE FOR THE POWER SOURCE DC +5V

ELECTICITY CONSUMED

2 mA

# 9) ACCESS SEQUENCE

To make this control pad interchangeable to present one, output will be TH and data will be picked out successively by changing TH Hi to Low as described below. These movements finish within 2 msec from the beginning of access. There are more than 10 msec period to start the next access.

I/O SET POINT FOR THE PORT

TH(bit6) TR(bit5) TL(bit4) R(bit3) L(bit2) D(bit1) U(bit0) out in in in in in

#### PAD DATA

. Similar to the data of present pad, data of this pad will be fixed by changing TH for  $2\mu\,\mathrm{sec}$ .

Data beyond 9 will not be guaranteed as illustrated in the table below.

When ending the access, be sure that TH is fixed to Hi.

Distinction between the present pad and the MD-2 pad is made by the distinction data.

			T	1			*	
	TH(bit6	TR(bit5	TL(bit4)	R(bit3)	L(bit2)	D(bit1)	U(bit0	X
1	Hi	TRG-C	TRG-B	RIGHT	LEFT	DOWN	UP	
2	Low	START	TRG-A	0	0	DO₩N	UP	1
3	Hi	TRG-C	TRG-B	RIGHT	LEFT	DOWN	UP	
4	Low	START	TRG-A	0	0	DOWN	UP	
5	Hi	TRG-C	TRG-B	RIGHT	LEFT	DOWN	UP	
6	Low	START	TRG-A	0	0	0	0	D <u>I</u> STI <u>N</u> CT
7	Hi	TRG-C	TRG-B	MODE	TRG-X	TRG-Y	TRG-Z	DATA
8	Low	START	TRG-A	1	1	1		EXTERNAL   DATA
9	Hi	TRG-C	TRG-B		•••	•••		

## 10) MECHANISM OF THE PARTS

D BUTTON	1 EA $\rightarrow$ 8 direction dome t	type(using rubber contact)
A BUTTON	1 EA → PUSH type	(using rubber contact)
B BUTTON	1 EA → PUSH type	(using rubber contact)
C BUTTON	1 EA → PUSH type	(using rubber contact)
X BUTTON	1 EA → PUSH type	(using rubber contact)
Y BUTTON	1 EA → PUSH type	(using rubber contact)
Z BUTTON	1 EA → PUSH type	(using rubber contact)
START BUTTON	1 EA → PUSH type	(using rubber contact)
MODE KEY	1 EA → PUSH type	(using tact switch)
PLUG	1 EA → 9P D-SUB PLUG	

